

SEA SWAT Sea Base Defense LCS

Total Ship Systems Engineering 2003



TSSE Presentation Outline

Introduction

Conclusions

Requirements & Design

Combat Systems Manning

Damage Control

Electrical

Hull

Modularity Propulsion





TSSE Knowledge Scheme

TS3000, 3001, 3003

Capstone Design Project

Realistic, Team-based

Application Courses

Systems Engineering Principles and Process

Integration Processes and Techniques

MS Degree (ME/Physics/ECE) — Foundation Engineering Understanding of Major Elements

TS4002,4

TS3002, 4000, 4001



2003 TSSE Faculty and Team Faculty Members

Professor Fotis Papoulias
Professor Mike Green

Team Members

LT Rodrigo Cabezas, Chilean Navy
LT Jake Didoszak, USN
LT Colin Echols, USN
LTJG Zafer Elcin, Turkish Navy
LT Constance Fernandez, USN
LTJG Alper Kurultay, Turkish Navy
LT Scott Lunt, USN
LT Freddy Santos, USN





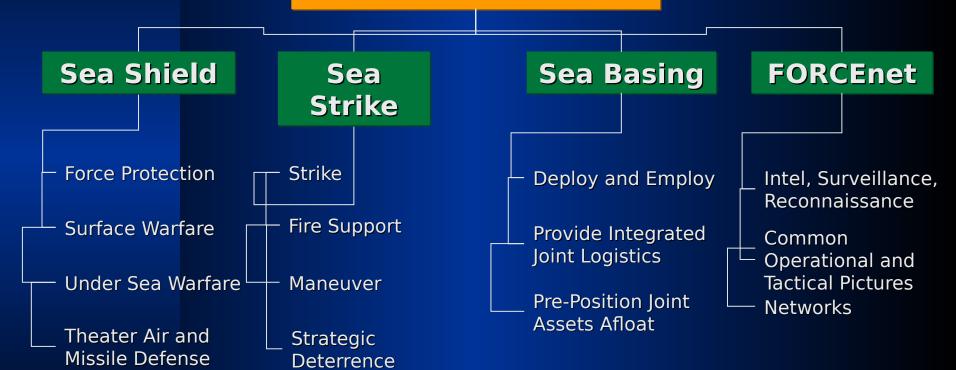
The Taskers

- Systems Engineering Analysis -Initial Requirements Document (SEA-IRD)
- TSSE Faculty Capstone Design Project Guidance
- N7 Preliminary Design Initial Requirements Document (N7 PD-IDD)





Sea Power 21







Sea Shield

Force Protection

Protect Against SOF and Terrorist Threats

Mitigate Effects of CBRNE

Surface Warfare

Provide Defense Against Surface Threats

Conduct
Offensive
Operations
against Surface
Threats

Under Sea Warfare

Neutraliże
Submarine Threats
in the Littorals

Provide Self-

Defense Against

Subsurface

Necestrize Open

Ocean Submarine

Threats

Counter Minefields

from Deep to

Shallow Water

Breach Minefields, Obstacles, and Barriers from VSW to the Beach Exit Zone

Conduct Mining Operations

Theater Air and Missile Defense

Provide Defense Against Air and Missile Threats

Provide Maritime Air and Missile Defense

Provide Overland Air and Missile

Defense

Conduct Sea-

Based Missile

Defense



Deploy and Employ

Close the Force & Maintain Mobility

Provide at Sea Arrival and Assembly

Allow Selective Offload

Reconstitute and Regenerate at Sea

Sea Basing

Provide Integrated Joint Logistics

Provide Sustainment for Operations at Sea

Provide Sustainment for Operations Ashore

Provide Focused Logistics

Provide Shipboard and Mobile Maintenance

_ Provide Force Medical Services

Provide Advanced Base Support

Pre-Position Joint Assets Afloat

Integrate and Support Joint Personnel and Equipment

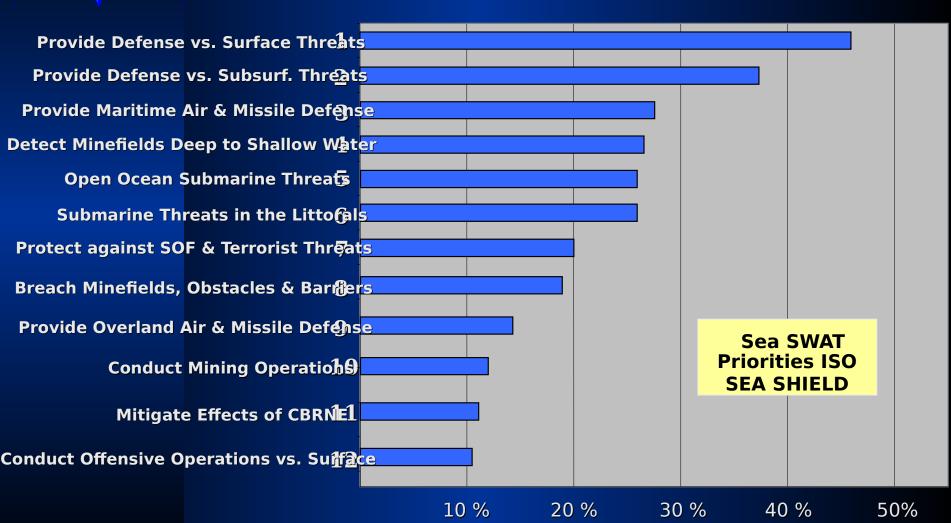
Provide Afloat C2 Physical infrastructure

Provide AFSB Capability for Joint Operations





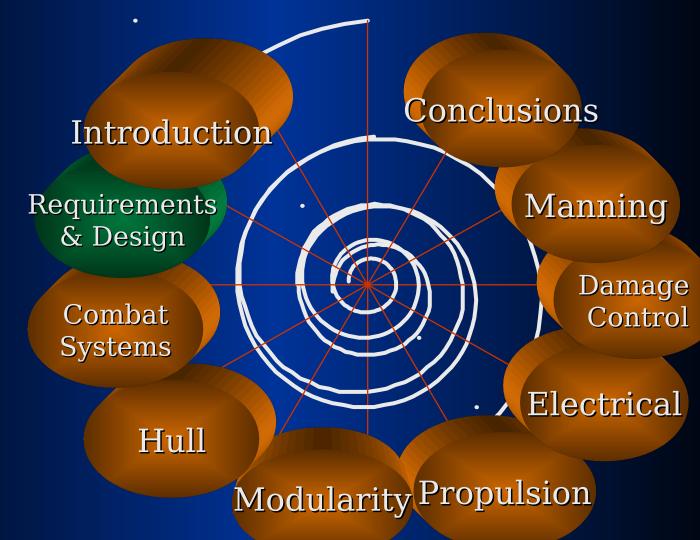
SEA SWAT Priorities



Total Ship Systems Engineering



Requirements







Design Project Guidance

...to produce a design for a ship or group of ships to protect the ships of the Sea Base while in the operating area

and

...protection of the airborne assets moving between Sea Base and the objective

and

...protection of the surface assets moving between Sea Base and the beach





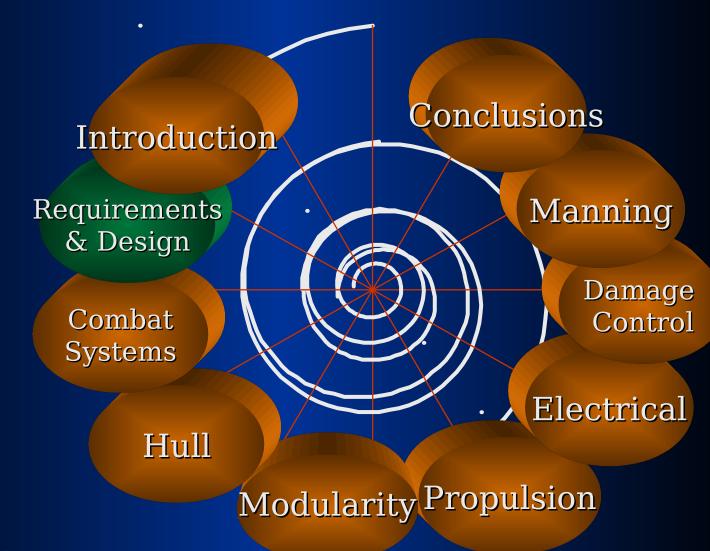
Requirements Overview

- Protect the Sea Base
- Operate in Deep to Very Shallow Water
- Operate at 35 knots
- AW, SUW, USW/MIW capable
- Reduced Manning implemented
- Modular Design





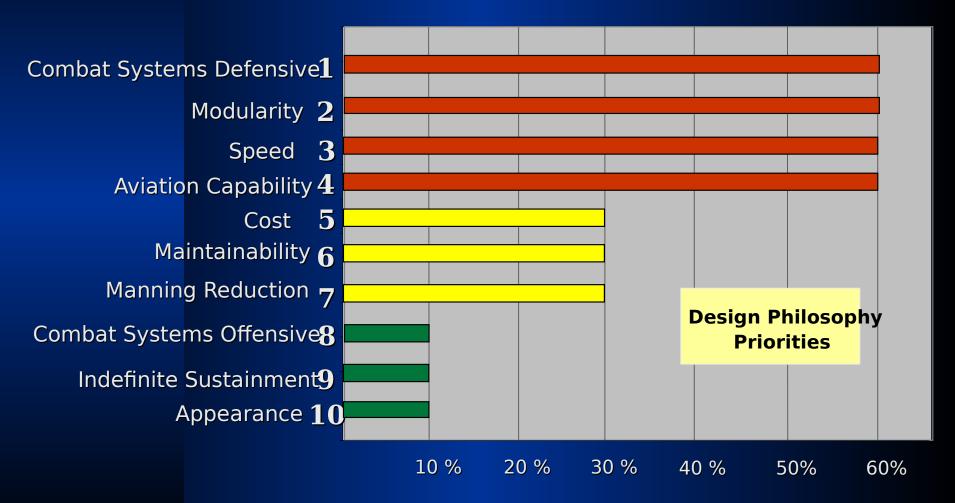
Design Philosophy







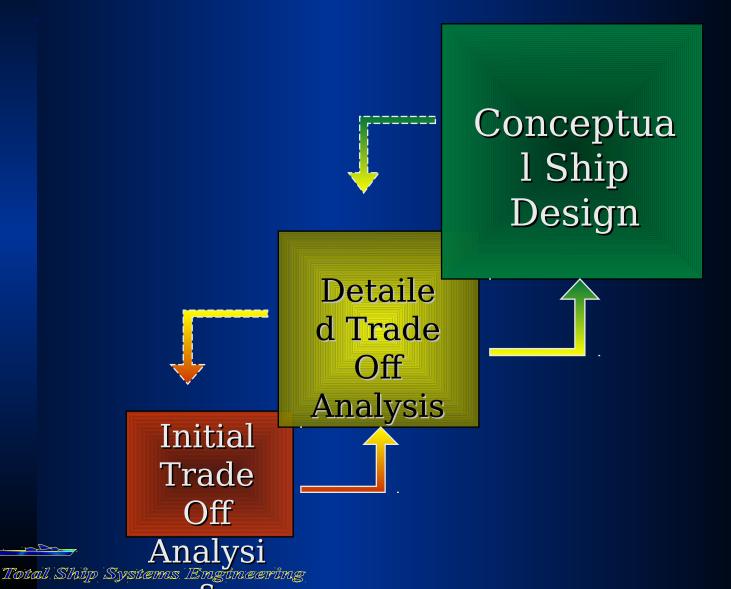
Overall Design Philosophy







Design Process





Courses of Action

COA #1: Single Ship Concept

COA #2: Two-Ship Concept

 Trade-off analysis conducted to determine which COA better meets requirements





Trade-off Analysis Priorities

- Operational Flexibility (10%)
- Operational Capability (10%)
- Operational Availability (10%)
- **Cost** (15%)
- Space Availability (15%)
- Acquisition (40%)





Cost Analysis*

Characteris tics	Single Ship (SUW, AAW, & USW/MIW)	Two Ship (SUW,USW/MIW & SUW/AAW)
Length	258 ft	249 ft
Beam	52 ft	50 ft
Draft	19.2 ft	18.5 ft
Power	39500 hp	36800 hp
Displacement	1626 LT	1454 LT
Est. Cost of Hull	\$450 M	\$425 M
Est. Cost of Combat Systems	\$225 M	\$212.5 M
Total Est. Systems Engineering	\$675ased or	\$637.5pPeadsReet



Single Ship vs. Two

Ships

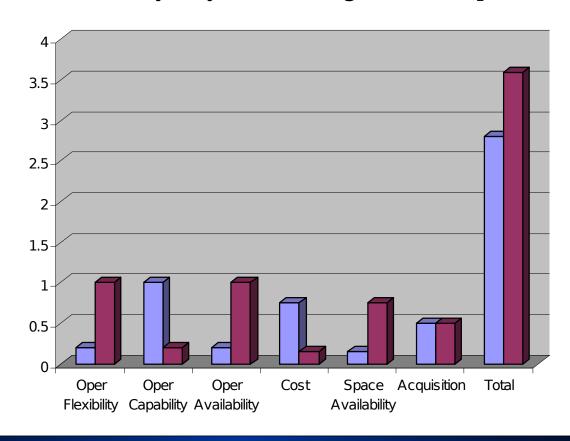
Priority	Single Ship Design	Two Ship Design
Operational Flexibility	.2	1
Operational Capability	1	.2
Operational Availability	.2	1
Cost	.75	.15
Space Availability	.15	.75
Acquisition	.5	.5
Total* *sum	of the 2product of and ra	f each 3ri6rity we





Single Ship vs. Two Ships

Feasibility Study Results for Single and Two-Ship LCS Design

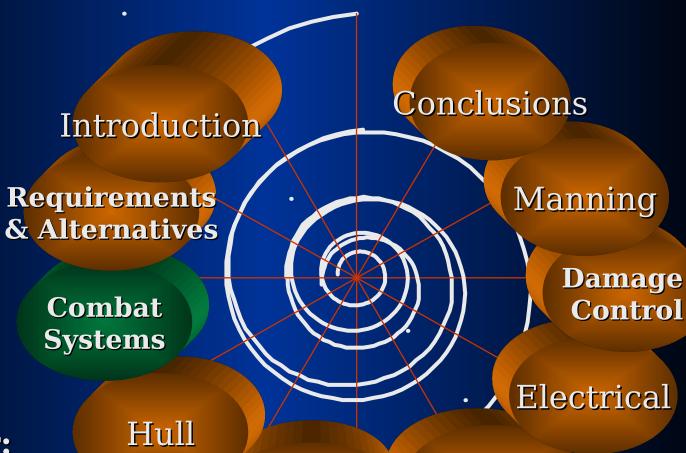


☐ Single Ship
☐ Two Ships





Combat Systems



Next
Speaker:
LT Rodrigo
Cabezas

Modularity Propulsion



Threats

Sea Base States

State I - Staging / Buildup (Op Area)

- ASCM
- Small boats
- Unconventional ships/boats
- Submarines/UUVs
- Mines

State II - Ship-to-Shore / Ship-to-Obj. Maneuver

- Small boats
- Mines
- SAMs
- Unguided munitions
- Aircraft/UAVs





Threats (cont'd)

Sea Base States

State III - Sustainment

- ASCM
- Mines
- Unconventional ships/boats
- SAMs
- Aircraft/UAVs





Initial Combat Needs Analysis

Aircraft						
UAV's						
SAM's						
ASCM						
USV's						
Small						
Boats						
Submari						
nes						
UUVs						
Mines						
Associate						
d	Multi-	Air	Surface	Mine	Variable	Torpedo
Threat	functi	Search	Search	Warfare	Depth	Early
Comba		Radar	Radar	Packag	Sonar	Warnin
System	Radar			e		g





Weapons Systems Trade

Off

	Threat	Scenari	Title	Description
	cen	ario	S	
	M1 Low & Slow ASCM	1	Submarine Launched M1 ASCM	Two LCS undergoing ASW operations close to SeaBase
	M1 Low & Slow ASCM	2	Four Surface/Air M1 ASCMs	LCS defending against airplanes attacking SeaBase
	M1 Low & Slow ASCM	3	LCS Engaged by M1 Coastal batteries	Two LCS undertaking mine sweeping to clear a passage from SeaBase to shore. Positioned 8 miles
>	M2 Low & Fast ASCM	4	LCS Engaged by MIG-29 Carrying T2 ASCM	ที่เพยาะประกับ escorting an ExWar ship,

LCS
self
defens
e
scenar
io



Simulation: LCS engaged by coastal batteries



S3: Scenario number 3

R1, R2: Sensor suites

D1, D2: Anti-missile

Missiles

G1, G2: Guns

Scenario	Sensor	Missile	Gun	Pra	
S 3	R1	Ď1	G1	0.927	
S 3	R1	D1	G2	0.965	
S 3	R1	D2	G1	0.936	
S 3	R1	D2	G2	0.942	
S 3	R2	D1	G1	0.952	
S 3	R2	D1	G2	0.942	
S 3	R2	D2	G1	0.942	
S 3	R2	D2	G2	0.959	

Pra: Probability of Raid Annihilation





Weapons Systems Trade Off

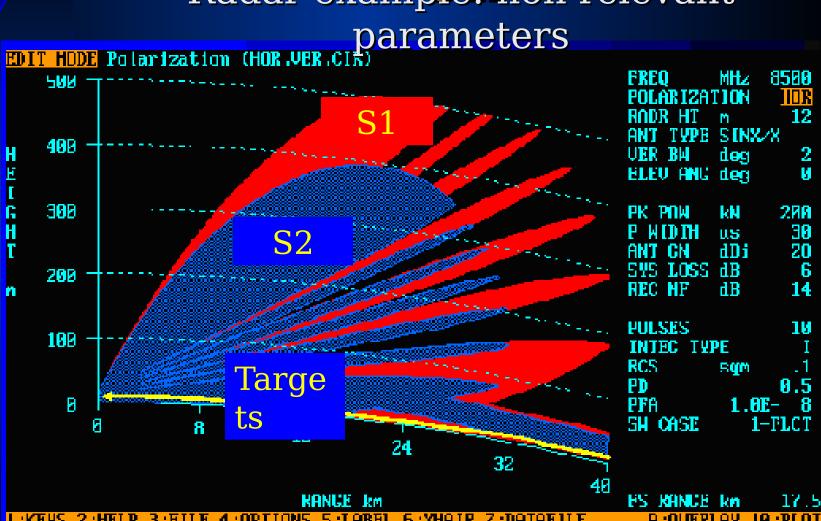
Radar example: S2, S1 Radars

Concept	S2	S1
Coverage (2D/3D)	3D	3D
Frequency/Band	X Band	C or S
Antenna/Aperture Type	Active Phased	Passive
Probability of Sensor Availability (RM&A)	0.95	0.85
Size/Weight Estimate	20000	10000
*Transition to Track Time	1	4
*Minimum Range (needs to match		
weapon)	50	250
Electrical Power Rqmts	350	200
Signature (RCS/IR) contribution	1	2
Systems quantity	1	3
Complexity	3	1



Weapons Systems Trade

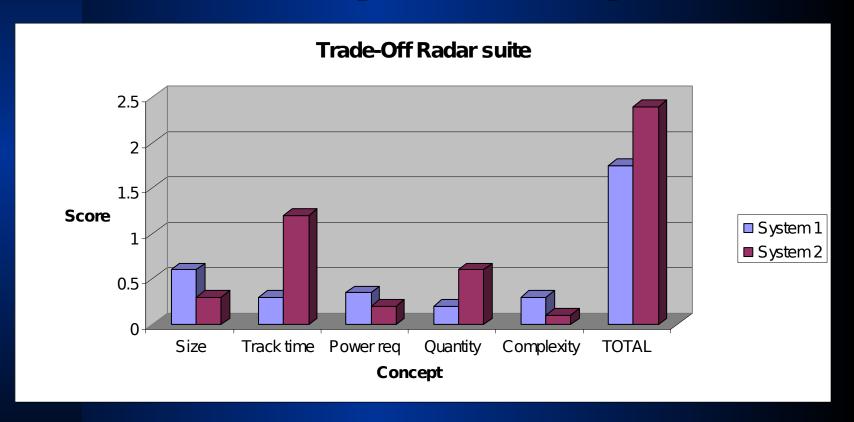
Radar example finon relevant





Weapons Systems Trade Off

Radar example: relevant parameters





Mission packages

- 1. Ship's payload limit: 160 LT (app)
- 2. Core package (CP)
 - Basic package (BP). Ship standard plus self defense.
 - Surface Warfare package (SUWP)
- 3. Anti Air Warfare package (AAWP)
- 4. Anti Submarine/ Mine Warfare package(ASW/MIWP)
- 5. Weapons systems Weight Limit:

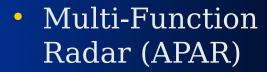




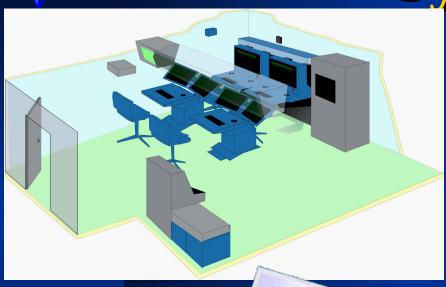


Core Mission Package

Systems Basic Package



- Command and Control System
- EW Suite
- Navigation Radar
- EO/IR/UV/LLTV Suite
- Communications Suite
- Hull Mounted Sonar
- Real Time Degaussing System









Core Package Systems

(cont) Basic

Basic Package

- Sea Ram
- Helicopter and UAV capable
- •Signature management system
- Nixie
- Torpedo warning receiver
- High precision







Core Package Systems (cont)



SUW Package

- Harpoon Missiles (x4)
- Mk III 57 mm BOFORS gun
- Rigid Hull Inflatable Boats (RHIB) (x2)



USW/MIW Mission Package

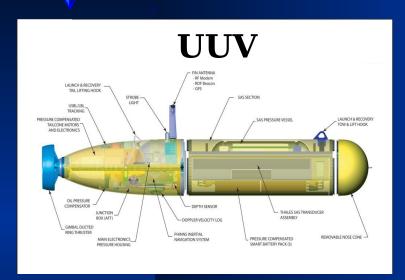


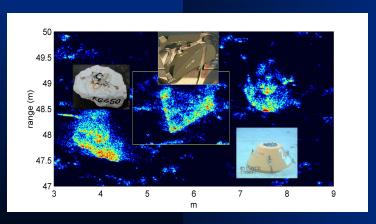
USW

- Mk 32 Mod 15 Torpedo Launcher
- Mk 50 Torpedoes (x 6)
- Low Freq Active Towed Sonar. (LFATS)
- LAMPS (aircraft sonar, sonobuoy and torpedo capable)



USW/MIW Mission Package





Advanced Side Looking Sonar (ASLS)

- Mine-Hunting UUVs
- Expendable Mine Destructor (EMD)
- Airborne Laser Mine Detector System (ALMDS)
- Rapid Airborne Mine Clearance System (RAMICS)
- Organic Airborne & Surface Influence Suite (OASIS)
- Airborne Mine Neutralization System (AMNS)



AAW Mission Package



AAW

- Mk 41 8-cellVertical LaunchingSystem
- Evolved SeaSparrow Missile (x32 using Mk 25Quad-Pack)

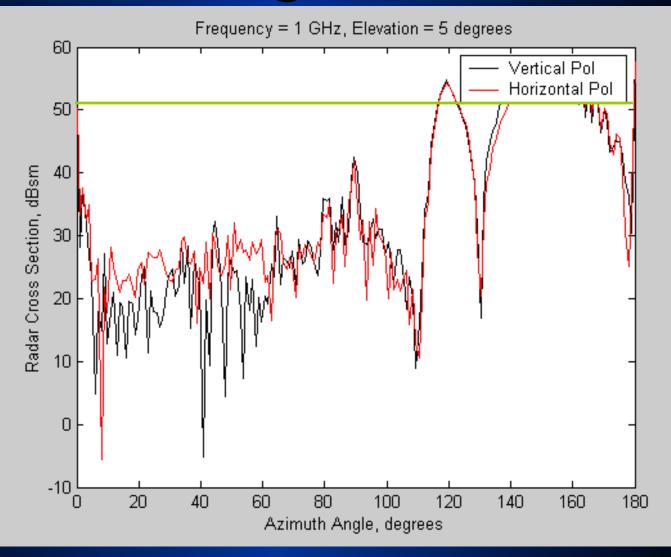


RCS

Freq: 1 GHz Elev: 5

deg

Signatures





Signatures (cont)

RCS

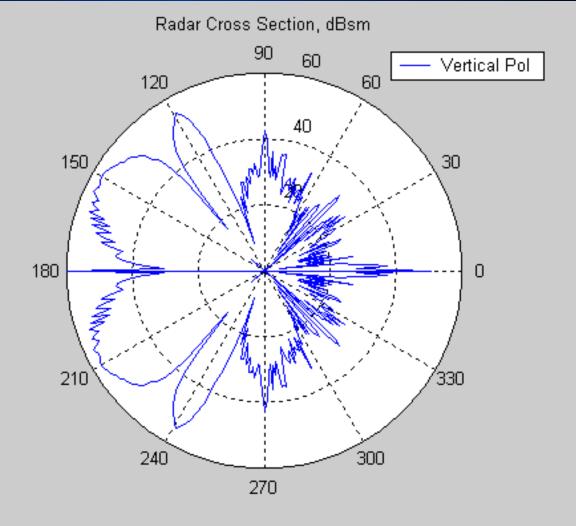
Freq: 1 GHz

Elev: 5

deg

Polar

graph



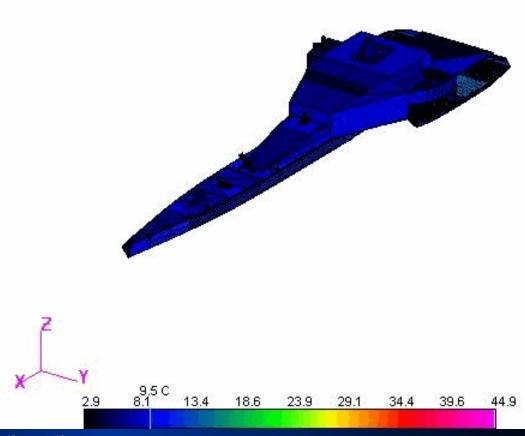
Azimuth Angle, degrees





Signatures (cont)

Temperature
Prediction
(Environmen
tal)





Signatures (cont)

IR
Signature
(10 Km,
staring
sensor)

Radiance





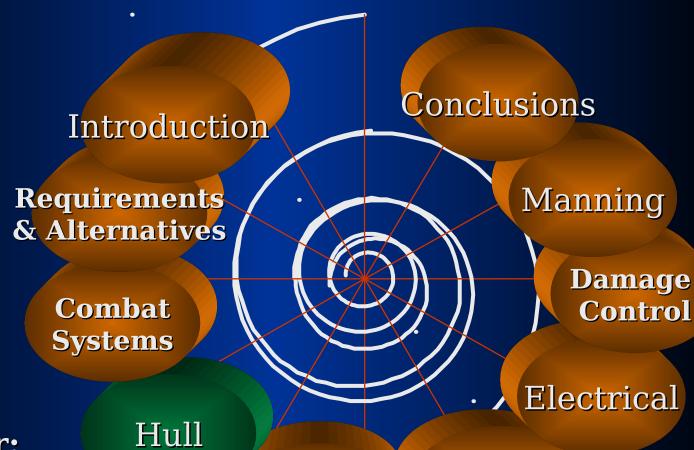
Summary

- Threats
- Scenarios
- Trade off
- Mission Packages
- Signatures





Hull Design



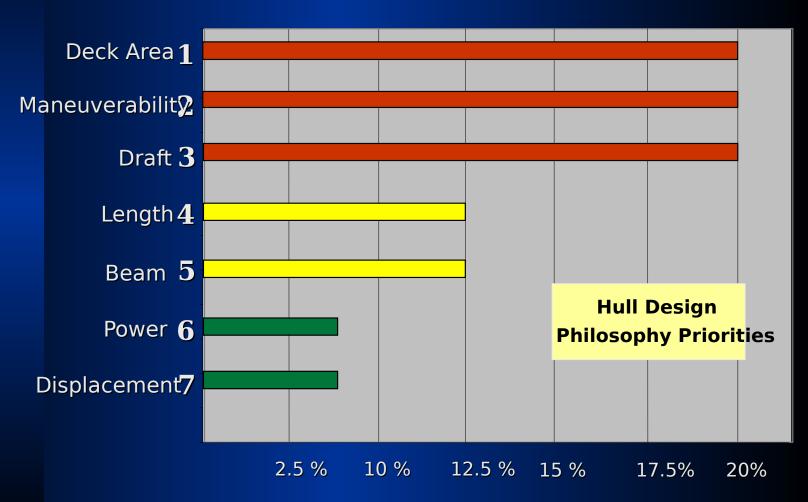
Next Speaker: LTJG Zafer Elcin

Modularity Propulsion





Initial Hull Design Philosophy



(%) Weight of each priority





Hull Form Candidates











Initial Hull Design Analysis

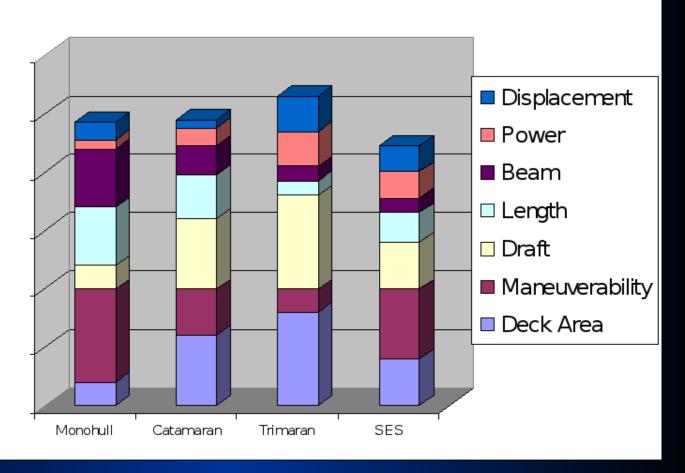
Priority	Monoh	Catamar	Trimaran	SES
	ull	an		
Deck Area	0.2	0.6	0.8	0.4
Maneuverabili	0.8	0.4	0.2	0.6
ty				
Draft	0.2	0.6	0.8	0.4
Length	0.5	0.375	0.125	0.25
Beam	0.5	0.25	0.125	0.125
Power	0.075	0.15	0.3	0.225
Displacement	0.15	0.075	0.3	0.225
Total	2.425	2.45	2.65	2.25





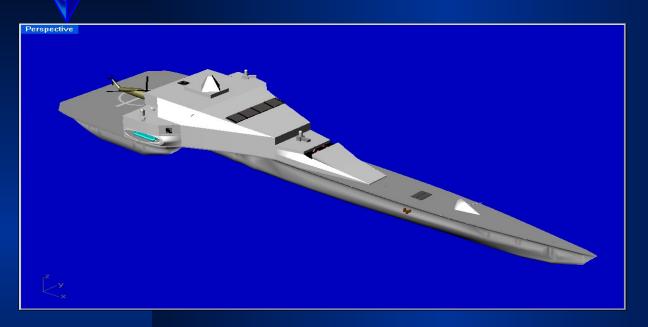
Initial Hull Design Analysis

Hull Design Analysis





Hull Design Processes







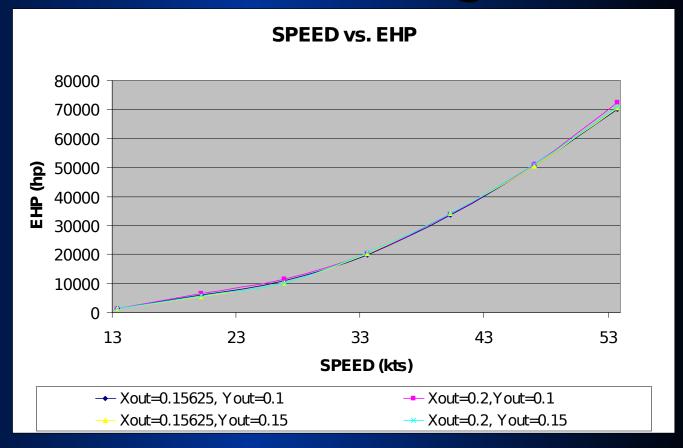
Advantages

- Resistance
- Seakeeping and Motions
- Maneuverability
- General Arrangement
- Survivability
- Signature Reduction





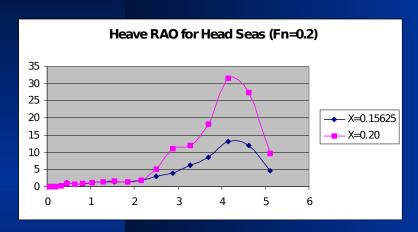
Side Hull Positioning Resistance and Powering

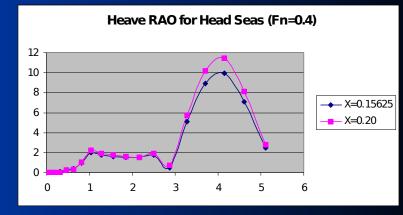


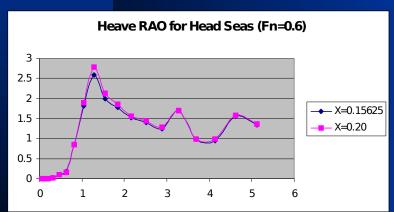


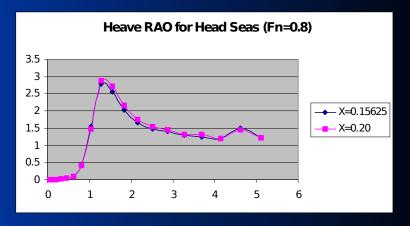


Side Hull Positioning – Seakeeping



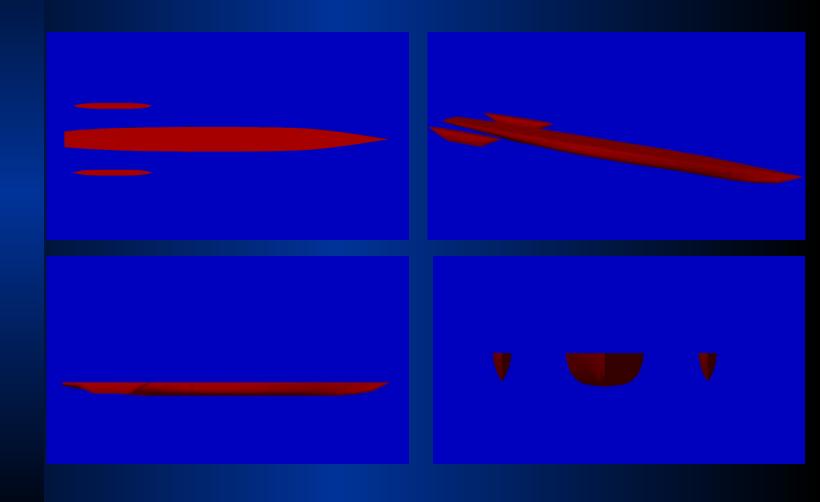








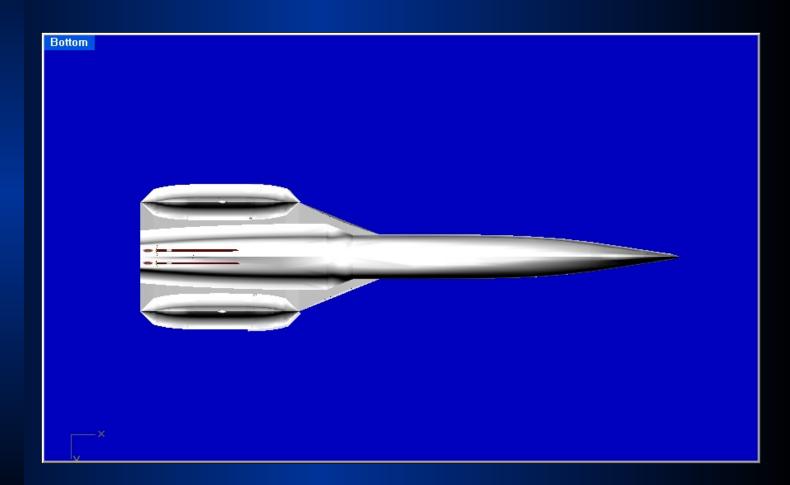
Side Hull Positioning







Side Hull Positioning







Characteristics of SEA

SWAT

Characteristic	Main Hull	Side Hull
Length (L _{BP})	400 ft	125 ft
Beam (B)	30.8 ft	7.5 ft
Total Beam for $Y_{out}/L_{pp}=0.1$	89.5 ft	
Draft (T)	12 ft	10 ft
L/B	13.0	16.7
$L/\tilde{N}^{1/3}$	9.39	7.54
Block Coefficient (C _B)	0.53	0.50
Midship Coefficient (C _M)	0.84	0.68
Waterplane Coefficient (C _w)	0.81	0.79
Volume	77226 ft³	4558ft ³
Displacement	2206 LT	130 LT
Total Volume	86343 ft ³	
Total Displacement	2466 LT	



Body Plan of SEA SWAT Main Hull

Body Plan of the Main Hull

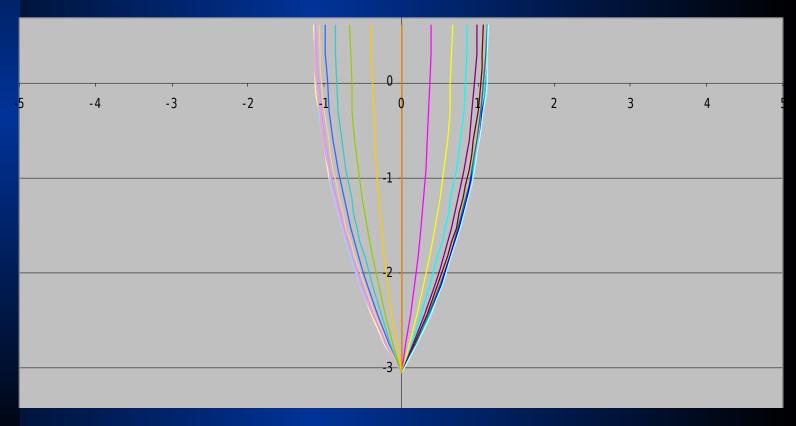






Body Plan of SEA SWAT Side Hull

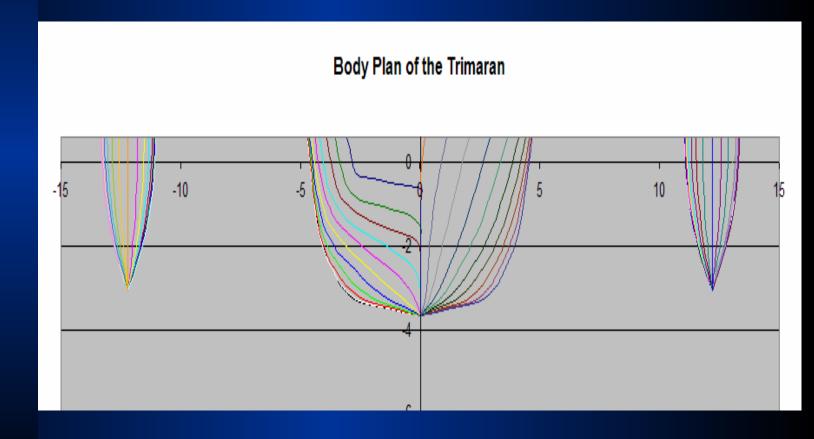
Side Hull Body Plan







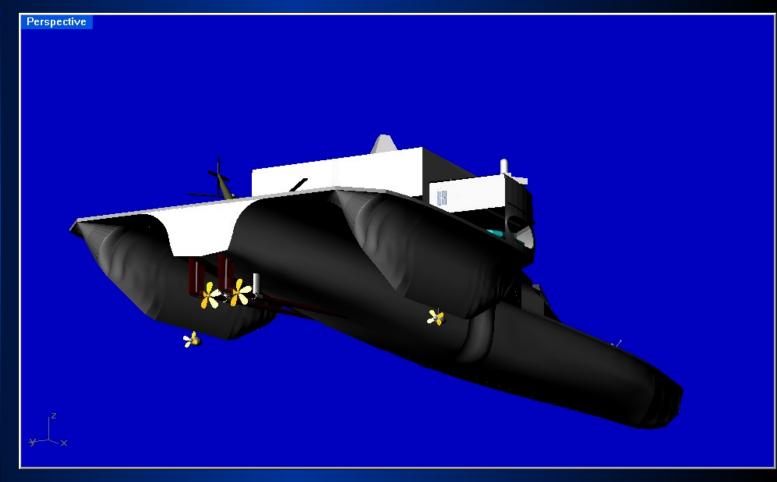
Body Plan of SEA SWAT





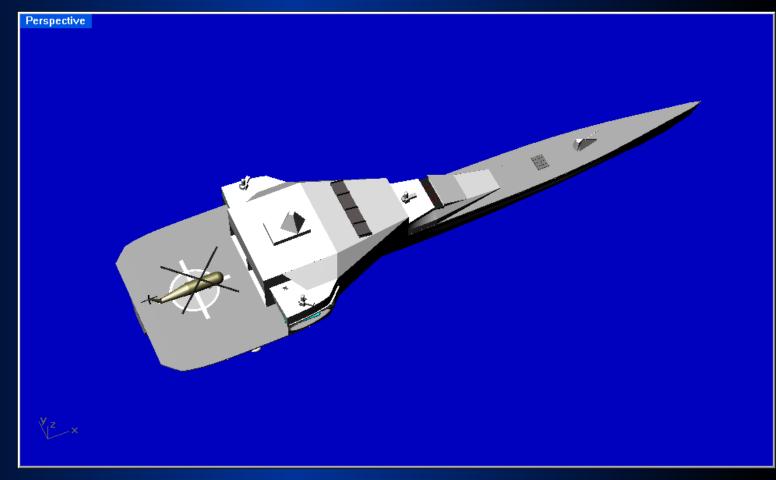


Maneuverability





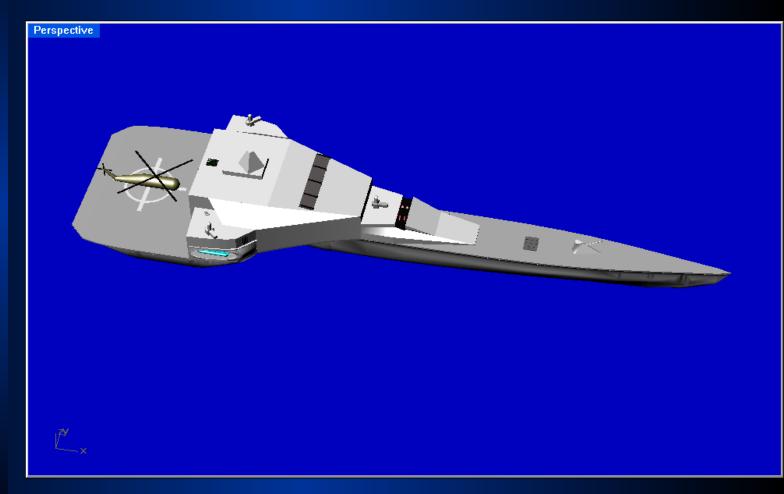
General Arrangement







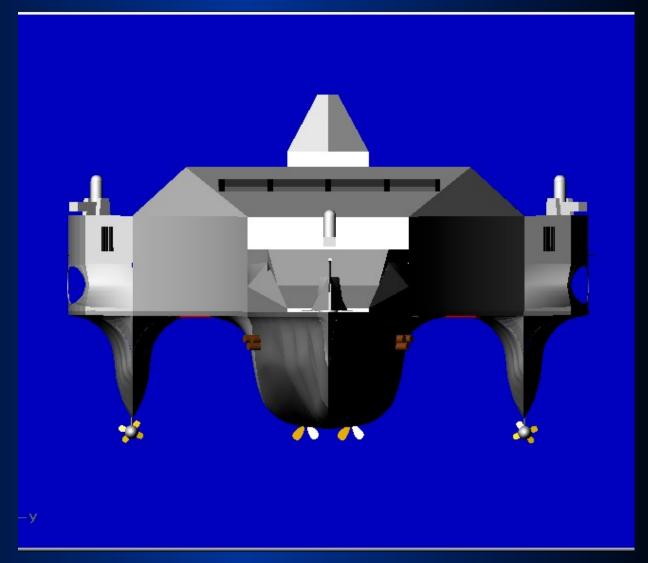
General Arrangement







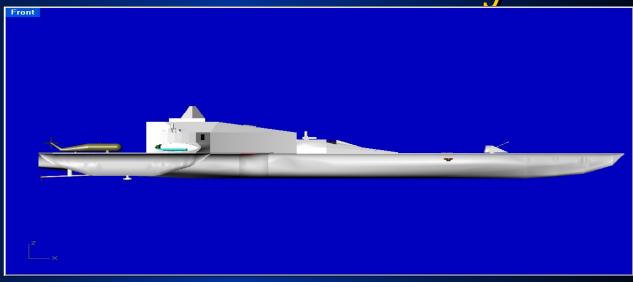
General Arrangement

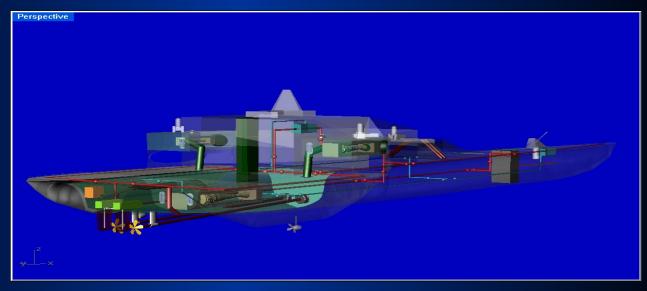






Survivability

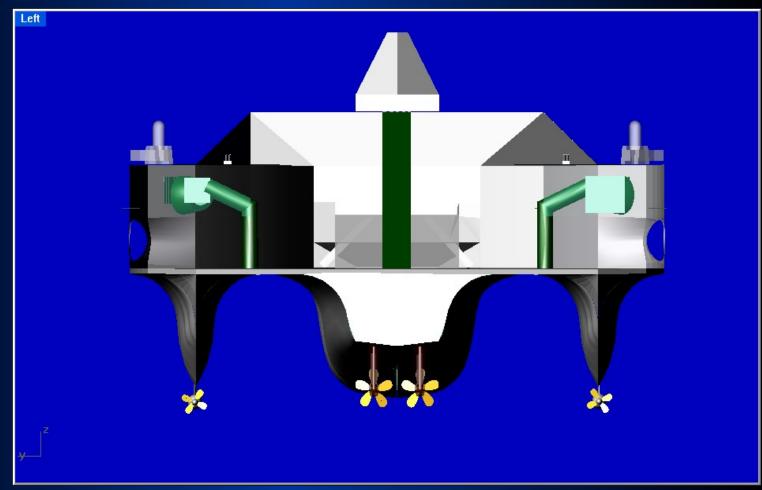






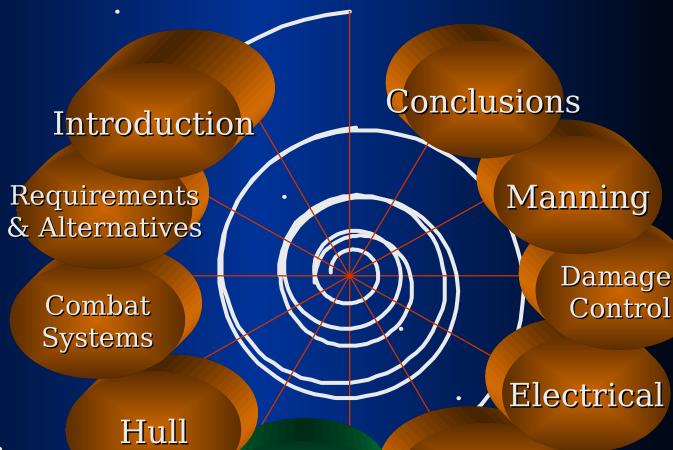


Signature Reduction





Modularity Design



Next
Speaker:
LT Scott
Lunt

Modularity Propulsion



Definition

Application to SEA SWAT

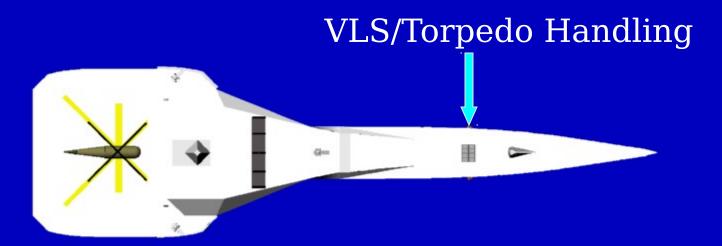




- Mission Packages
 - AW
 - USW/MIW
- Core Systems

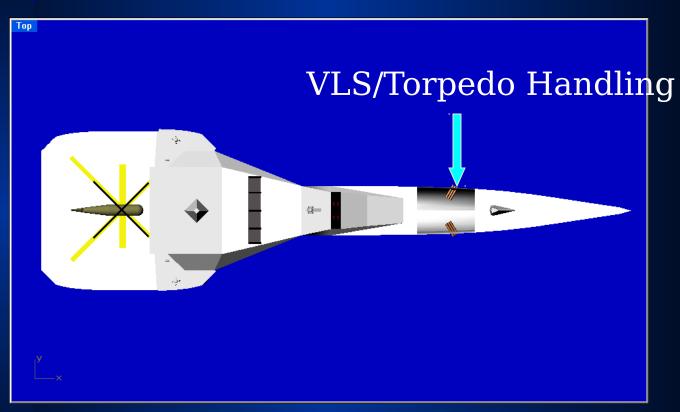






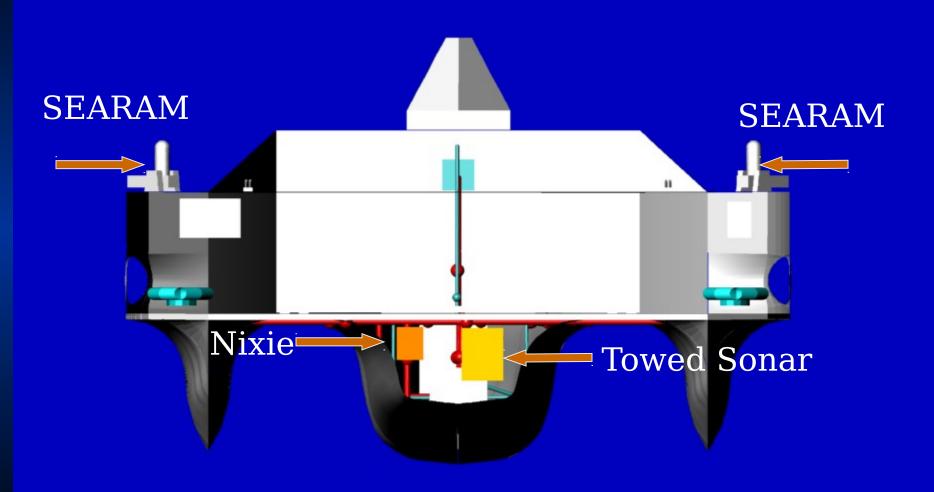






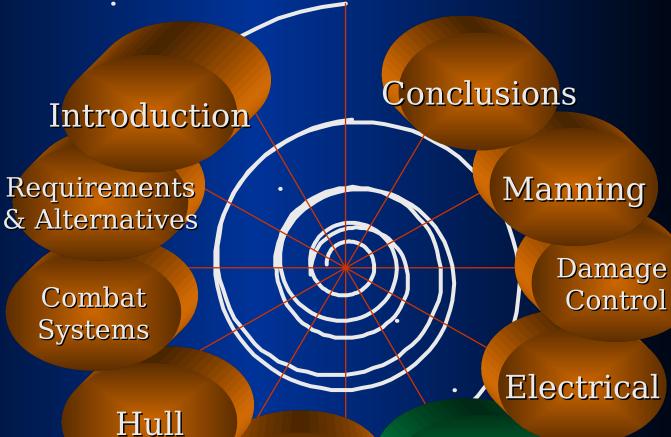








Propulsion Design



Next Speaker: LTJG Alper Kurultay

Modularity Propulsion



Approach

- Resistance Calculations and Power Requirements
- Selections
 - Propulsion Plant
 - Prime Mover
 - Propulsor
 - Propeller
- Trade-Offs
 - MT 30 vs. LM 2500(+)
 - LM 1600 vs. LM 2500(+) for Endurance Speed Calculations
- Fuel Consumption and Endurance Speed Calculations
- Layout Plan





Resistance Calculations

- Wave Resistance
 - Ship Wave Analysis Code
- Frictional Resistance
 - Based on ITTC57 Formula
- Form Resistance
 - Percent of the Frictional Resistance





Power Requirements



24 Hour Ship Electric Load = $5000 \text{ Hp} (\sim 3.7 \text{ MW})$





Alternatives for Propulsion Plants

- Conventional Steam Plant
- Nuclear Steam Plant
- Fuel Cells
- Diesels
- Gas Turbines





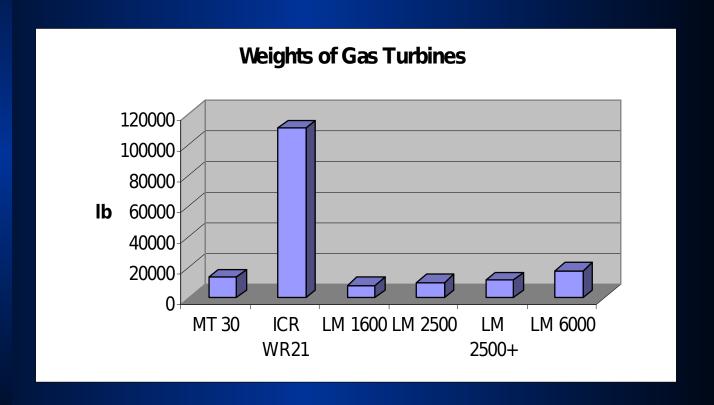
Prime Mover Selection

- ICR WR21
- LM 1600
- LM 2500
- LM 2500+
- MT 30 Trent





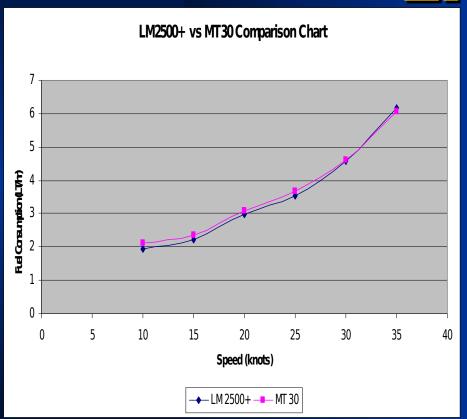
Comparison of Gas Turbines

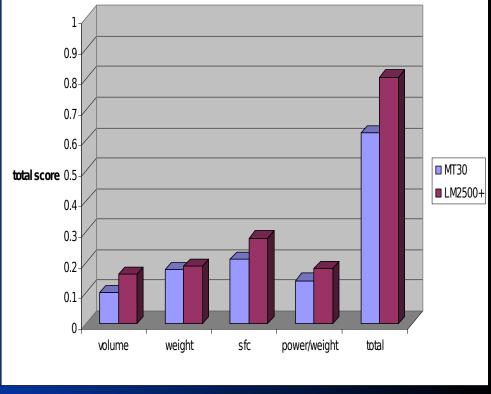






Trade Off Study Between MT30 and LM2500(+)

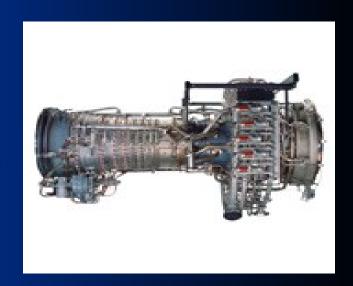






Final Decision

- 1 LM2500+
- 1 LM1600
- 1 Allison AG9140 (Harbor Duty)



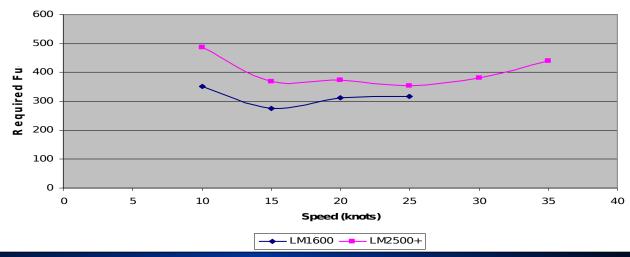


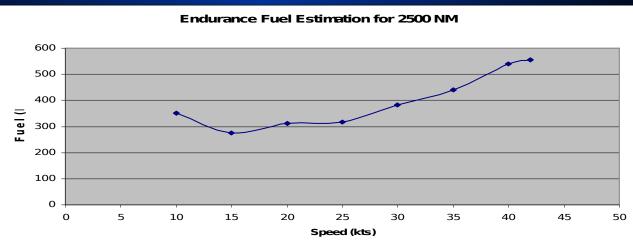






Fuel Consumption Calculations









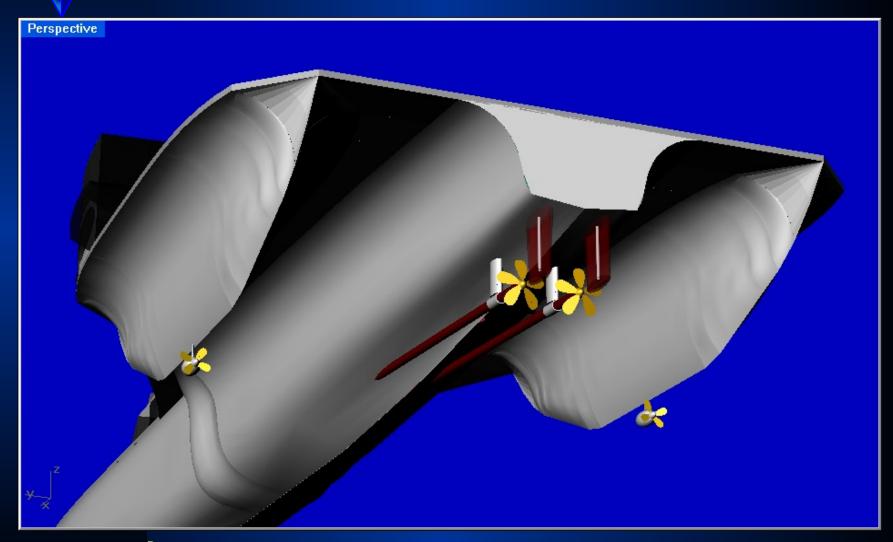
Propulsor Choices

- Podded Propulsors
- Water jets and hydro drive
- Conventional Propeller



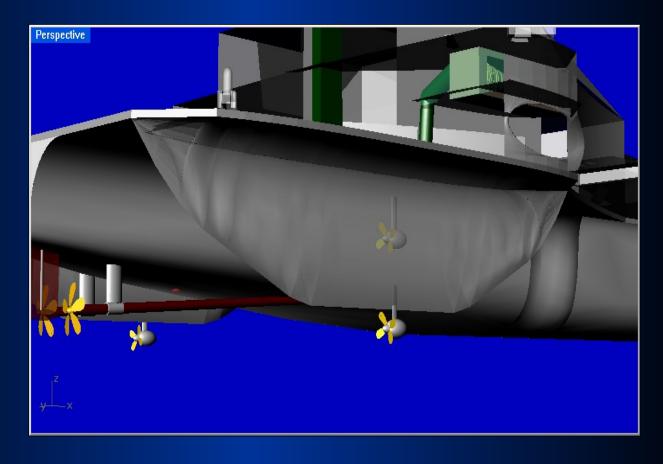


Propeller Selection





Retractable Rudder Propellers





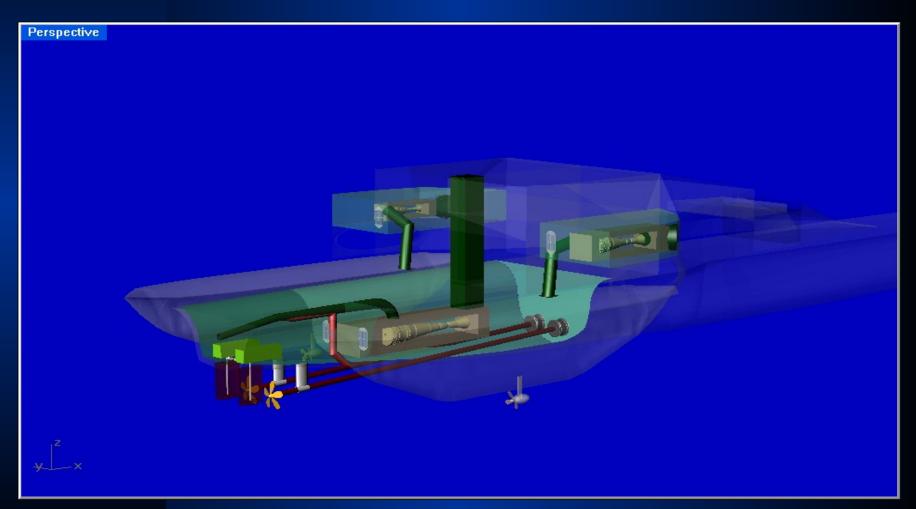
Propulsion Motor Selection

- Conventional motors
- HTS AC synchronous motors
- DC Super Conducting Homopolar motors



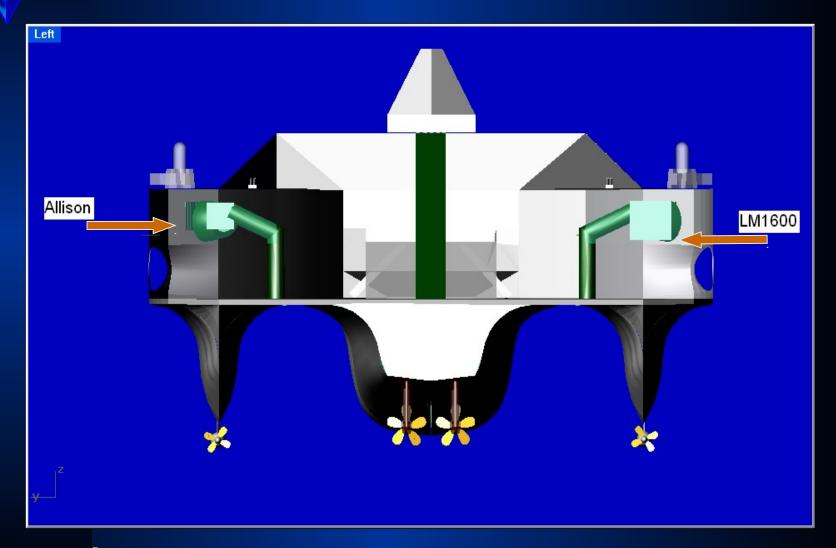


Engine Rooms Layout

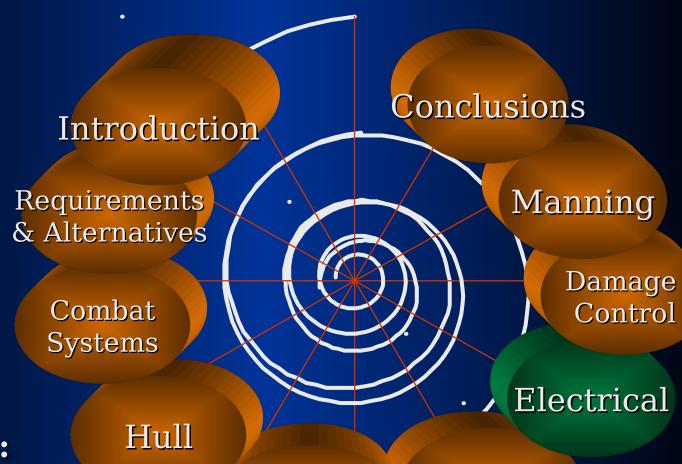




Engine Rooms Layout





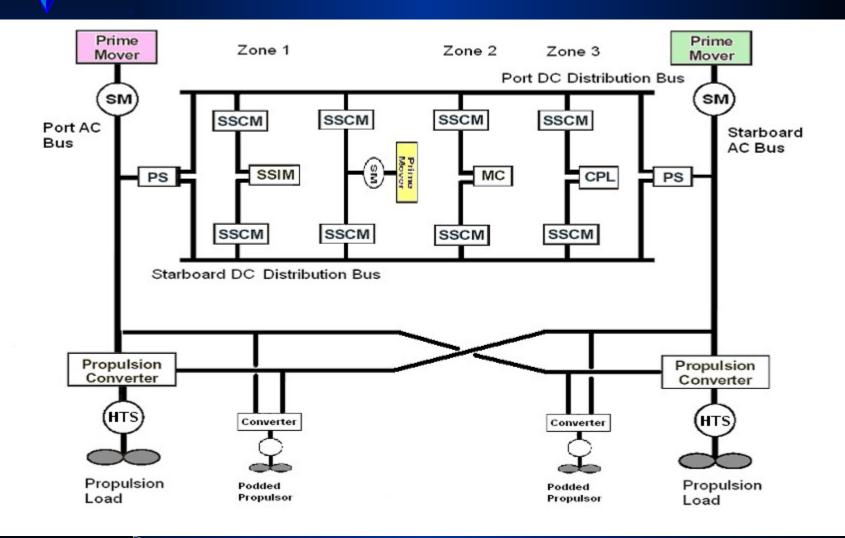


Next
Speaker:
LT Freddy
Santos

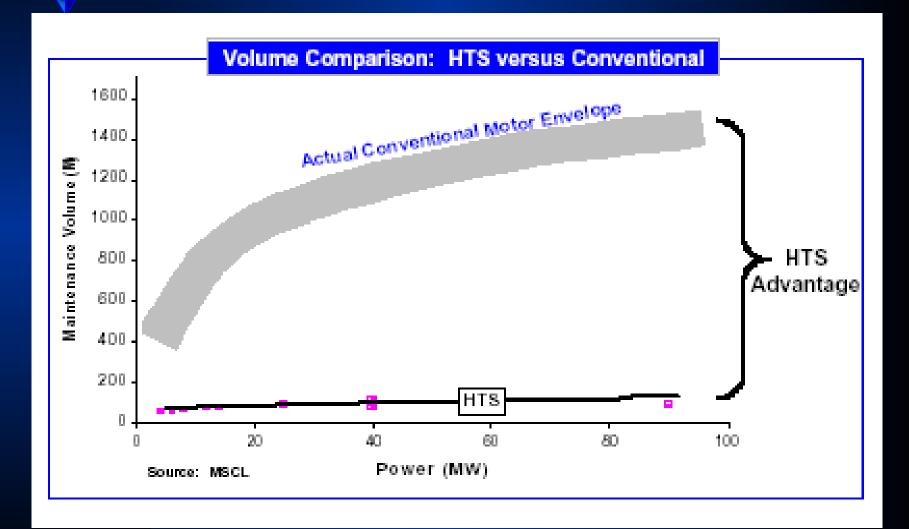
Modularity Propulsion





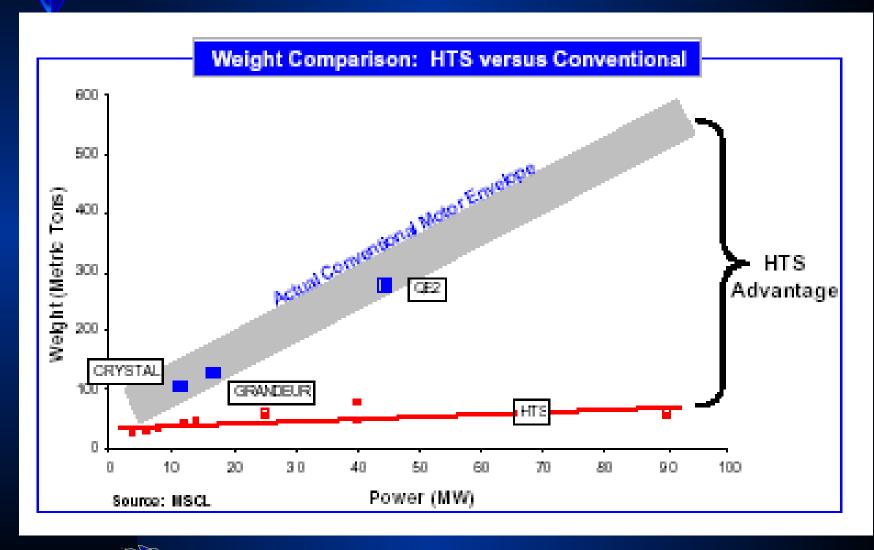






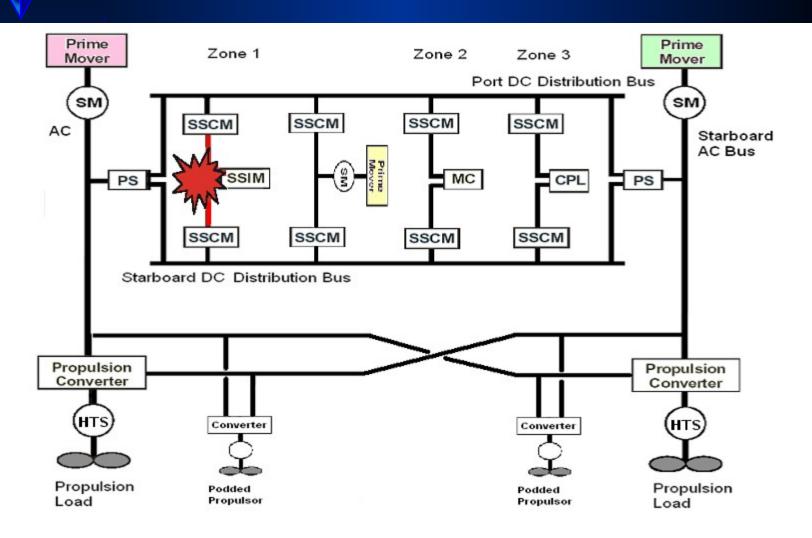




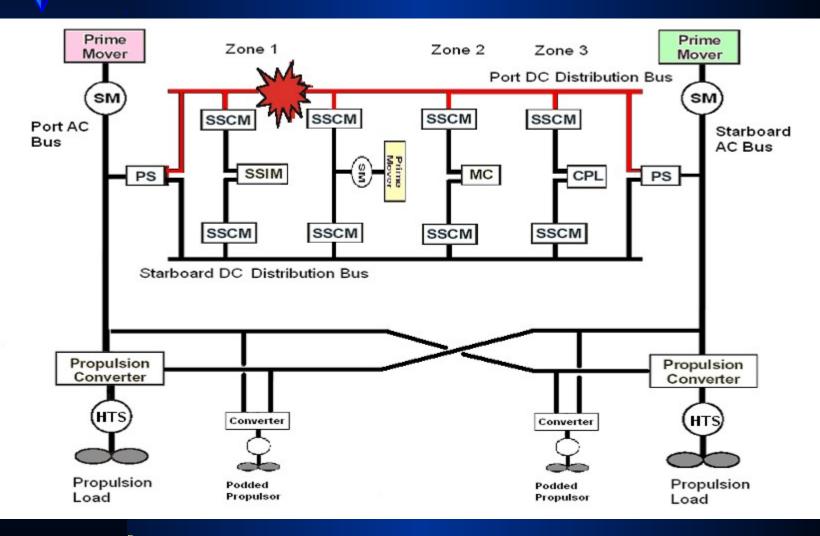




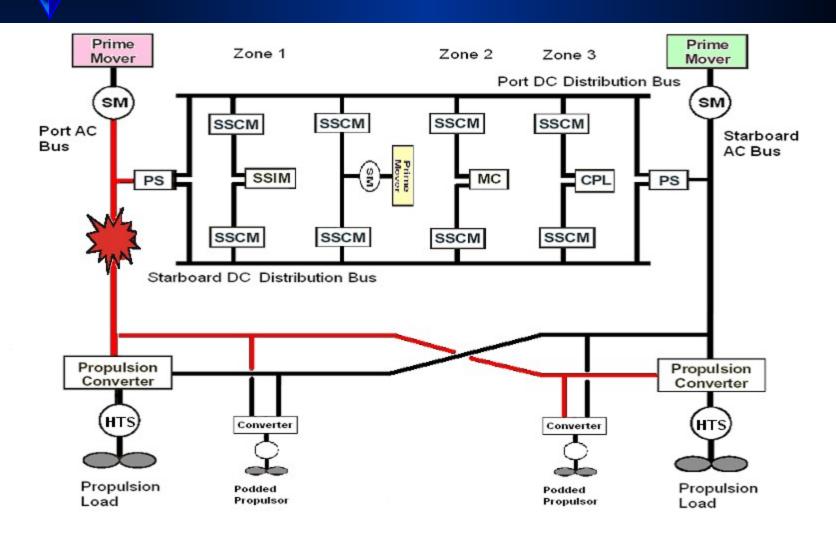














Damage Control

Conclusions Introduction Requirements Manning & Alternatives Damage Combat Control **Systems** Electrical Hull

Next **Speaker:** LT Jake **Didoszak**

Modularity Propulsion



Damage Control Philosophy







Prevent Casualties

- Shipboard Virtual Reality DC Training
- Integrated Zonal Compartmentalization
 - Electrical
 - Mechanical
- Remote Sensing Systems
 - Embedded Damage Sensing Syst
 - Space CCTV/Video Monitoring
 - Point Detection System (CBR)

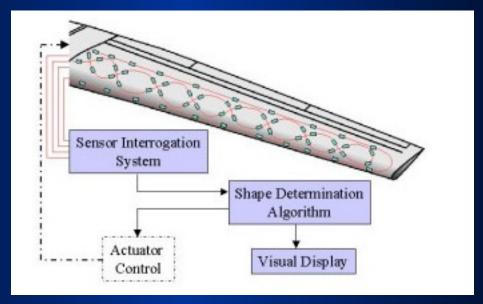






Evolving Technologies

Fiber Optic Embedded Wing Shape Sensing



- EmberNet Wireless-Networking System
- Embedded Temperature Sensing
- Infra-Red Flame Detection Sensors





Damage Sensor Matrix

Compartment	Infra-	CCTV/	Liquid	Fiber Opt/
	red	Video	Level	Embedded
CIC	X			
Bridge	X			
Offices	X			
Berthing	X		X	X
Galley & Messing	X	X		
Passageways	X			X
Electronics rooms	X	X		
Pump rooms	X	X	X	X
AC&R rooms	X	X	X	X
Paint lockers	X			
Engine enclosures	X	X		
Machinery spaces	X	X	X	X
Magazines	X	X	X	
Hangar	X	X		
Flight deck		X		



Combat Casualties (FIRE)

- Automated First Response
 - Water Mist System
 - FM-200 (Fire Suppression)
 - CO₂ Flooding
 - AFFF
- Human System Interfact
 - Personnel tracking system
 - Shipboard Wide Area Network
 - SEED for all watchstanders





Automated Response Matrix

Compartment	FM 200	CO2	Water Mist	AFFF
CIC	X			
Bridge	X			
Offices	X			
Berthing			X	
Galley & Messing			X	
Passageways			X	
Electronics rooms	X	X		
Pump rooms	X	X		
AC&R rooms	X	X		
Paint lockers	X	X		
Engine enclosures	X	X		
Machinery spaces	X	X	X	X
Magazines			X	X
Hangar			X	X
Flight deck				X



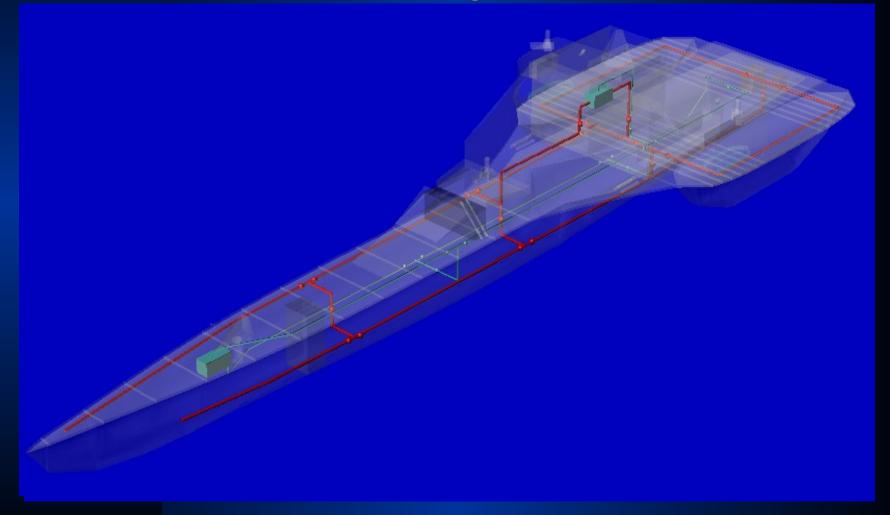
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 - SEED for all watchstanders
 - Shipboard Wide Area Network





Firemain and AFFF Systems





Combat Casualties

- Damage Control Parties
 - Two Repair Lockers
 - Video/sensor investigation
 - Secondary line of response



- Utilityman crosstraining
- Reduced overall manning





Restore from Casualties

- Zonal systems
 - Damage Control (FM, AFFF, CPS)
 - Mechanical (CW, VENT, compartment isolation)
 - Electrical (integrated distributed power grid)
- Self-healing systems
 - Buoyancy foam filler
 - Quickset patches
 - Kevlar cladding
 - Installed smoke ejectors
 - Installed drainage and educ





CBR - Layered Defense



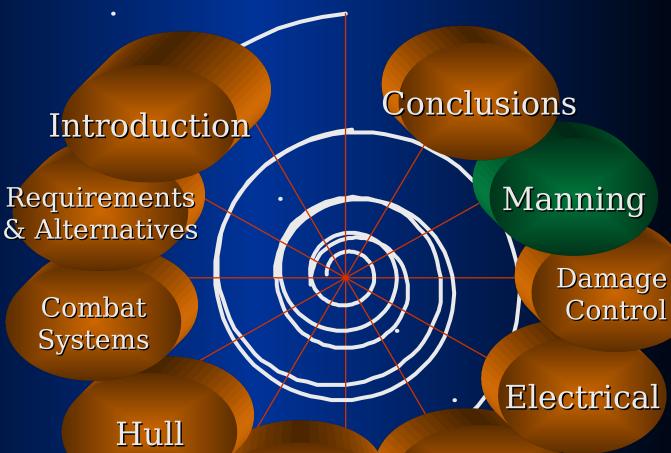


Damage Control Summary

- Increased use of Automatic response systems
- Real-time situational awareness through SWAN
- More unmanned machinery/electrical spaces
- Model & Simulate to predict damage progression
- Use of COTS Damage Control systems
- Greater survivability through better compartment/zonal segregation







Next Speaker: LT Constance

Modularity Propulsion

Fernandez, Systems Engineering



- Manning levels determined based on
 - Watch Stations
 - Maintenance
 - Logistics Operations requirements
- Focused on Reduced Manning
 - Low maintenance design
 - Increased skill level of crew





Condition I Watch Bill

STATION LOCATION	AAW	USW
PILOT HOUSE/SIGNAL BRIDGE	3	3
CO/XO	2	2
COMBAT	9	9
AAW	3	
USW		4
WEAPONS/SUPPORT	11	11
CCS/DC	4	4
ENGINEERING	7	7
REPAIR 1	21	21
REPAIR 2	21	21
FLIGHT DECK	5	5
HELO FIRE FIGHTING	11	11
HELO DETACH		
CORPSMEN	6	6
MESSING	4	4
SUPPLY	4	4
TOTAL	111	112

	AAW	USW
Without Repair Parties	54	55
2 Section Rotation	108	110
Repair Parties	57	57
Required Manning	165	167
Required Berthing		
(Helo Detachment of		
10 persons)	175	182

SHIP	LENGTH (FT)	CREW
FFG -7	445	300
DDG-51	505	320
TRIDENT	560	175



- MAINTENANCE:
 - Condition Based Maintenance
- COMBAT SYSTEMS:
 - Multi-function Radar two maintenance men, no operators
 - Software for system is "self-diagnostic" and "self healing"
- ENGINEERING:
 - Integrated Electric Drive
 - Electrical Distribution System (fully automatic)





- DAMAGE CONTROL:
 - SWAN(Shipboard Wide Area Network)
 - Automated Identification
 Technology
 - Information Systems
 - Sensors
 - Virtual Training
 - Automated Response
 - Systems that are "self-diagnostic" and "self healing"



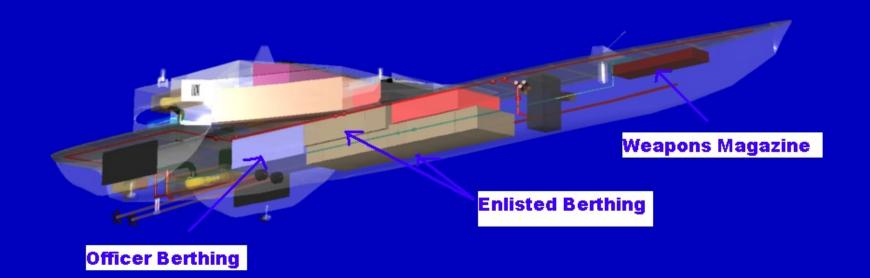


- Summary of Reduced Manning
 - Low maintenance/operator design
 - Use of more Sensors
 - Use of self diagnostic systems
 - Increasing skill level of ship crew





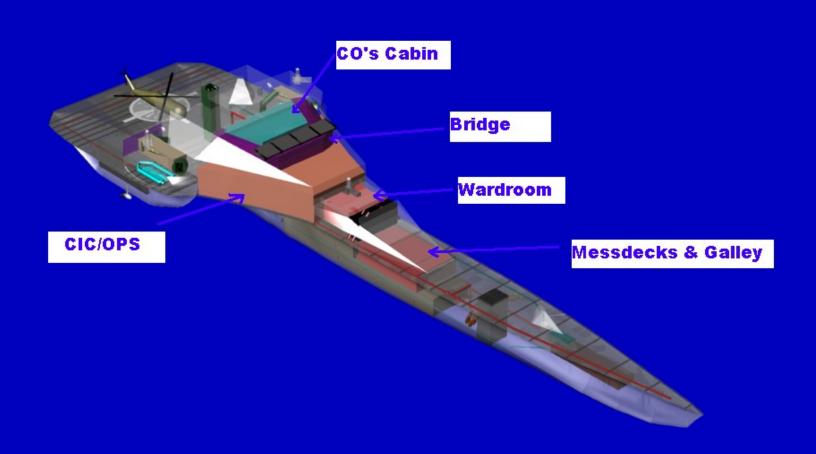
Space Allocation





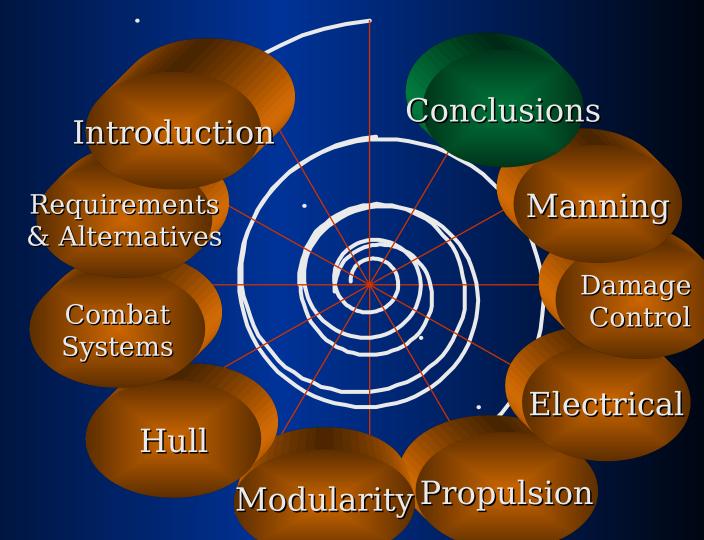


Space Allocation





Conclusions

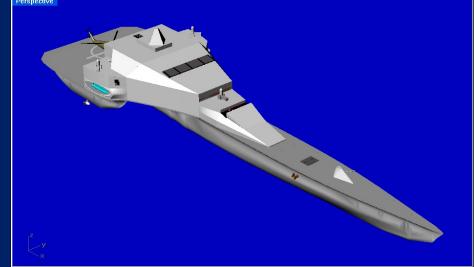






Closing Remarks

- All Requirements Met
- Trade-off Analyses Conducted
- Design Spiral Completed at least once
- Ship Loaded with Combat Systems







Closing Remarks

- Weight Estimations
- Cost ~\$655 M
- Hydrostatics
- Environmental Concerns
- Further Pursuits
- http://www.nps.navy.mil/tsse





Conference Room 3rd Deckof MAF Building B13391